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## LETTER TO THE EDITOR

# Partial structure factors of multicomponent alloys in the long-wavelength limit 

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#### Abstract

With the aid of a functional equation the long-wavelength limits of partial structure factors of multicomponent systems are expressed in terms of compressibility and dilatation factors. This generalises similar formulae for a binary system discovered by Bhatia and Thornton.


In recent years substantial progress has been made in both theory and experiment in the study of the partial structure factors of binary alloys. In particular the formulae of Bhatia and Thornton (1970) which express the long-wavelength limits of partial structure factors in terms of thermodynamic quantities were applied successfully to $\mathrm{Na}-\mathrm{K}$ alloys (Bhatia et al 1973). The formulae are useful not only for checking the consistency of experimental data but also for constructing proper models (Bhatia et al 1973, Bhatia and March 1975). Therefore we feel it appropriate to extend the formulae in anticipation of future applications to multicomponent systems.

The starting equation is (Bhatia and Ratti 1976)

$$
\begin{equation*}
\partial\left(\ln \rho_{i}\right) / c_{j} \partial\left(\beta \mu_{j}\right)=\delta_{i j} / c_{i}+a_{i j}-1 \tag{1}
\end{equation*}
$$

where $\rho_{i}, c_{i}$ and $\mu_{i}$ stand respectively for density, mole fraction and chemical potential of a multicomponent system containing $n$ species of molecules. $a_{i j}$ is the longwavelength limit of a partial structure factor as defined, for example, in Bhatia et al (1973). From the chain rule of partial differentiation it follows that

$$
\begin{equation*}
\frac{\partial\left(\ln \rho_{1}, \ln \rho_{2}, \ldots, \ln \rho_{n}\right)}{\partial\left(\mu_{1}, \mu_{2}, \ldots, \mu_{n}\right)}=\frac{\partial\left(\ln \rho_{1}, \ln \rho_{2}, \ldots, \ln \rho_{n}\right)}{\partial\left(p, c_{2}, \ldots, c_{n}\right)} \frac{\partial\left(p, c_{2}, \ldots, c_{n}\right)}{\partial\left(\mu_{1}, \mu_{2}, \ldots, \mu_{n}\right)} . \tag{2}
\end{equation*}
$$

Using the definitions

$$
\begin{align*}
& K_{T}=\left(\frac{\partial \ln \rho}{\partial p}\right)_{T, c_{2}, \ldots, c_{n}}  \tag{3}\\
& \delta_{i}=\left(\frac{\partial \ln \rho}{\partial c_{i}}\right)_{p, T, c_{i \omega i}} \tag{4}
\end{align*}
$$

it is easy to show that the matrix elements of the first Jacobian on the right-hand side

[^0]of (2) are given by
\[

$$
\begin{align*}
& \frac{\partial\left(\ln \rho_{i}\right)}{\partial p}=K_{T}  \tag{5}\\
& \frac{\partial\left(\ln \rho_{1}\right)}{\partial c_{i}}=-c_{1}^{-1}+\delta_{i}, \quad i \neq 1 \tag{6}
\end{align*}
$$
\]

and

$$
\begin{equation*}
\frac{\partial\left(\ln \rho_{i}\right)}{\partial c_{j}}=\frac{\delta_{i j}}{c_{i}}+\delta_{j}, \quad i \neq 1 \tag{7}
\end{equation*}
$$

In equations (3) and (4) $\rho$ denotes the total density, $K_{T}$ is the isothermal compressibility and $\delta_{i}$ is a dilatation factor (Bhatia and Thornton 1970). The second Jacobian on the right-hand side of equation (2) is the inverse of $\partial\left(\mu_{1}, \mu_{2}, \ldots, \mu_{n}\right) / \partial\left(p, c_{2}, c_{3}, \ldots, c_{n}\right)$ whose matrix elements are easily obtained by partial differentiation using the standard thermodynamic relation:

$$
\begin{equation*}
\mathrm{d} g=-s \mathrm{~d} T+\mathrm{d} p / \rho+\sum_{i=2}^{n}\left(\mu_{i}-\mu_{1}\right) \mathrm{d} c_{i} \tag{8}
\end{equation*}
$$

where $g$ and $s$ are respectively specific free energy and entropy, $p$ is the pressure. The results are

$$
\begin{array}{ll}
\partial \mu_{1} / \partial p=\left(1+\sum_{k=2}^{n} c_{k} \delta_{k}\right) \rho^{-1} & \\
\partial \mu_{1} / \partial c_{i}=-\sum_{k=2}^{n} g_{i k} c_{k}, & i \neq 1 \\
\partial \mu_{i} / \partial p=\left(1+\sum_{k=2}^{n} c_{k} \delta_{k}\right) \rho^{-1}-\delta_{i} / \rho, & i \neq 1, j \neq 1 \\
\partial \mu_{i} / \partial c_{j}=-\sum_{k=2}^{n} g_{j k} c_{k}+g_{j i}, & \tag{12}
\end{array}
$$

where $g_{i k}$ stands for $\partial^{2} g / \partial c_{i} \partial c_{k}$. Inverting the matrix to obtain the second Jacobian of equation (2). multiplying the two Jacobians on the right-hand side of equation (2) together and then substituting the results into equation (1) we obtain

$$
\begin{equation*}
\delta_{i j} / c_{i}+a_{i j}-1=\rho k_{\mathbf{B}} T K_{T}+\langle\delta| \mathbf{A}|\boldsymbol{\delta}\rangle+\langle\delta| \mathbf{A}|j\rangle / c_{i}+\langle i| \mathbf{A}|\boldsymbol{\delta}\rangle / c_{i}+\langle i| \mathbf{A}|j\rangle / c_{i} c_{i} \tag{13}
\end{equation*}
$$

where bras and kets are vectors of $(n-1)$ components defined by
$|\delta\rangle=\left(\begin{array}{c}\delta_{2} \\ \delta_{3} \\ \delta_{4} \\ \vdots \\ \delta_{n}\end{array}\right), \quad|2\rangle=\left(\begin{array}{c}1 \\ 0 \\ 0 \\ \vdots \\ 0\end{array}\right), \quad|3\rangle=\left(\begin{array}{c}0 \\ 1 \\ 0 \\ \vdots \\ 0\end{array}\right), \ldots, \quad|n\rangle=\left(\begin{array}{c}0 \\ 0 \\ 0 \\ \vdots \\ 1\end{array}\right)$

$$
|1\rangle=-|2\rangle-|3\rangle-\cdots-|n\rangle .
$$

$|2\rangle,|3\rangle, \ldots,|n\rangle$ are unit vectors along the coordinate axes and the matrix $A$ has an
inverse which satisfies

$$
\begin{equation*}
\left(\mathrm{A}^{-1}\right)_{i-1, i-1}=\beta g_{i j} . \tag{15}
\end{equation*}
$$

Specialising the above three equations to a binary alloy one immediately recovers the equations of Bhatia and Thornton. Hence they are the generalisations that we search for.

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